

AN IEC 61000-4-30 CLASS A - POWER QUALITY MONITOR WITH A FLICKER METER BASED ON HILBERT TRANSFORM

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Abstract: This paper provides a novel analysis to implement a demodulation technique based on discrete Hilbert transform. Running on a DSP floating point architecture mounted in the power quality instrument PQ1000 ECAMEC fulfills the requirements of IEC61000-4-30, Class A category, over all the electrical measured parameters. Several analysis of optimal filter design and performance of signal processing are presented.

Key words: Hilbert transform, complex envelope tracking, frequency measurement, IEC 61000-4-15.

1. MATHEMATICAL FLICKER MODEL AND COMPLEX DEMODULATION

Accurate modeling of voltage flicker is a crucial task before any envelope tracking algorithm can be applied. A simplified mathematical expression of voltage flicker is expressed in (1).

$$v(t) = A(t) \cdot \cos(2\pi ft + \alpha) \quad (1)$$

where A(t) is the magnitude of voltage under flicker disturbance, f, the supplied frequency and α , phase angle.

The time variant amplitude waveform A(t) depends on the load variability pattern. Its shape can be a step function to represent the heavy loads switching, as it can be a square or sinusoidal wave with a certain composition of frequency, or present non periodic waveform as the disturbances caused by large arc furnaces.

The goal of this study is tracking the instantaneous phasor to estimate its amplitude and phase each time a new sample of voltage waveform is acquired.

2. THE COMPLEX ENVELOPE TRACKING

The algorithm to measure complex envelope (CE) is based on the discrete Hilbert transform (HT). It is a useful mathematical tool to describe the complex envelope of a real-valued carrier modulated signals [2][3]. The CE term in this application will be named Instantaneous Phasor (IP).

The first step on signal processing is developed under the HT which provides the IP magnitude and angle. The magnitude is the voltage envelope measurement at a certain time, spectrally composed by a DC and AC components. The DC value is the sum of the amplitudes of the mains

frequency and its harmonics, and the AC components is the sum of each modulation frequency amplitude (inter-harmonics) present on the point of common coupling (PCC) at the electric network.

The IP angle is the voltage angle measured at a certain time. While the main frequency component remains larger than the harmonics components, the estimated instantaneous phasor angle represents the phase of power system frequency at the PCC.

3. HILBERT TRANSFORM THEORY

The HT is defined for real signals as (2a), with its equivalent Fourier transform (FT) in (2b).

$$x_{HT}(t) = x(t) * \frac{1}{\pi t}$$

$$X_{HT}(\omega) = -j \cdot \text{sgn}(\omega) \cdot X(\omega) = \begin{cases} -j & \text{for } f > 0 \\ +j & \text{for } f < 0 \end{cases} \quad (2a \text{ y } 2b)$$

where $-j \cdot \text{sgn}(\omega)$, has the effect of shifting the negative frequency components of $x(t)$ by $+90^\circ$ and the positive frequencies components by -90° , Fig. 1(a). The mentioned instantaneous phasor correspond to the analytical signal composed by the real signal and the Hilbert transform shifted 90° (3).

$$IP(t) = x(t) + j \cdot x_{HT}(t) \quad (3)$$

The Fourier transform of HT process is depicted on Fig. 1. The analytical signal and envelope response is shown in Fig. 1(d)

As an example the following equations (4a - 4b) express how the analytical expression helps in tracking the voltage envelope and phase from the PCC.

$$u_{red} = A(t) \cdot \cos[\omega_0 t] \xrightarrow{HT} u_{red}^{HT} = A(t) \cdot \sin[\omega_0 t]$$

$$IP(t) = u_{red} + j \cdot u_{red}^{HT}$$

$$IP(t) = A(t) \cdot (\cos[\omega_0 t] + j \cdot \sin[\omega_0 t]) \quad (4a)$$

$$IP(t) = A(t) \cdot e^{j\omega_0 t}$$

$$IP(t) = U_{RMS} \sqrt{2} (1 + A_{FLK} \cdot \sin[\omega_{FLK} t]) \cdot e^{j\omega_0 t}$$

$$A(t) = |IP(t)| = U_{RMS} \sqrt{2} (1 + A_{FLK} \cdot \sin[\omega_{FLK} \cdot t])$$

$$\delta(t) = \text{angle}|IP(t)| = \arctg \left| \frac{\text{imag}(IP(t))}{\text{real}(IP(t))} \right| = \omega_0 \cdot t \quad (4b)$$

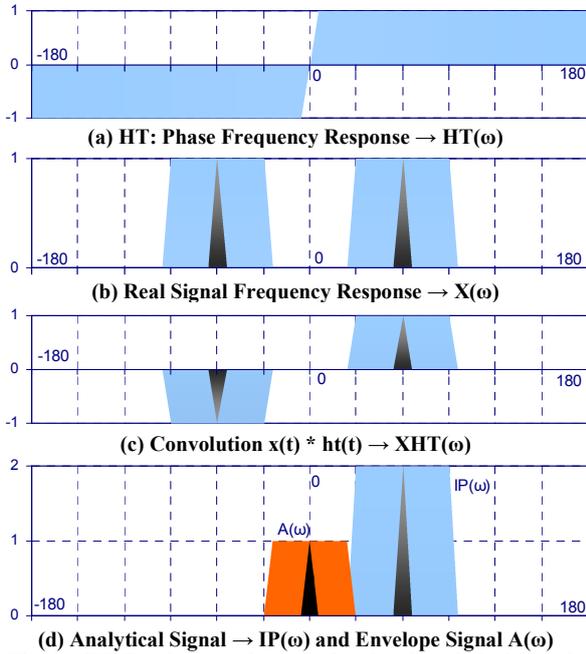


Fig. 1 HT Fourier transformed of real and analytical Signals

The IP components are shown in Fig. 2, at left side the cosine signal is superimposed to its Hilbert transform, a cosine shifted $\pi/2$, i.e. a sine signal. Both signals compose the analytical expression. At right side, the analytical expression is represented on the polar graph. Each time the signal is sampled, the information of amplitude and phase angle is plotted with an arrow (10 samples per cycle).

The signal sampling frequency (FS) must be constant, however this consideration do not guarantee an equidistant angular between phasors. This angle is powerful information about the voltage phase angular speed at the PCC. Angular and frequency measurement is developed at point 9 of this work.

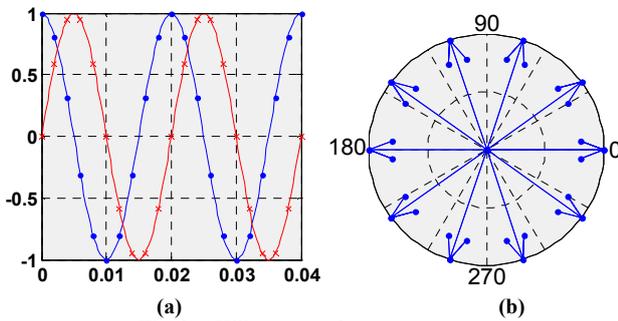


Fig. 2 Hilbert transform components

- (a) Signal Components Analytical Equation: $\text{Signal} + j \text{HT}[\text{Signal}]$
 (b) Polar representation of IP: $A(t) \perp \delta(t)$

A 50Hz mains frequency signal with 10 Hz flicker frequency modulation is shown in Fig. 3. The information of IP is decomposed at **¡Error! No se encuentra el origen de la referencia.** in its polar components: instantaneous amplitude and instantaneous angle. Furthermore, the IP

information is represented at a polar chart in Fig. 5. Far from developing a unit circle (normalized), the amplitude is governed by the flicker phenomena.

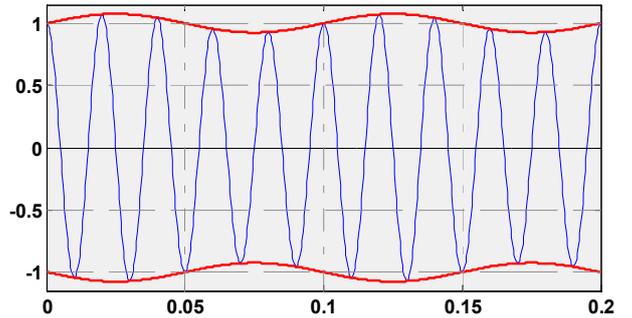
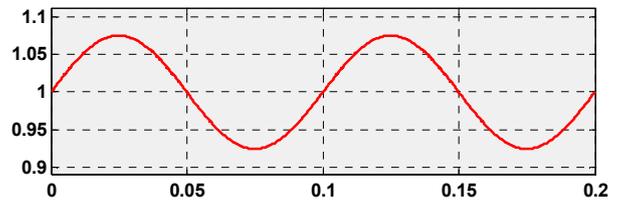
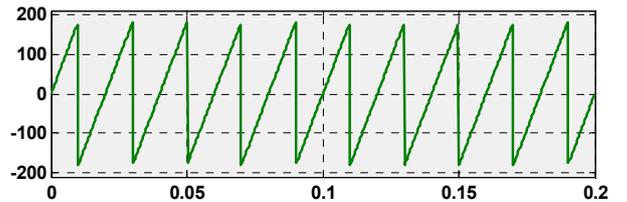


Fig. 3 Voltage on presence of flicker
Power and Flicker frequency: 50Hz and 10 Hz respectively.



(a) Amplitude of instantaneous phasor



(b) Phase angle of instantaneous phasor

Fig. 4

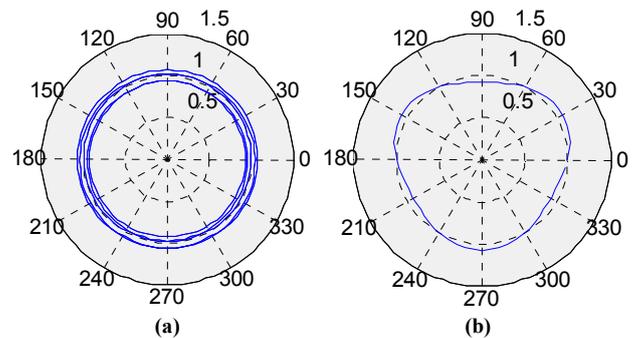


Fig. 5 Phasors amplitude of Voltage flicker

4. HT – DIGITAL FILTER IMPLEMENTATION

A digital Hilbert transform technique is implemented on a floating point DSP architecture. The filter adopted is a FIR filter with odd symmetric coefficients, designed in Matlab with Parks – McClellan algorithm (using the Remez exchange algorithm and the Chebyshev approximation theory [4]). Filters designed in this way demonstrate an equiripple behavior in there frequency response.

The filter length, N (number of coefficients), affects the accuracy of amplitude and phase tracking, and the speed of calculations. The longer the filter length, the minimal tracking error, but more calculations are required. The

optimal length filter was carried out in a flicker-meter simulation performed on Matlab. The study included the performance analysis of demodulation at different amplitudes and frequencies of voltage modulation, considering quantized signals and filter coefficients at 24 bits.

The sampling frequency of the instantaneous phasor block is equal to 3200 samples/s, on a 24 bit ADC. The FIR HT filter length is 513 coefficient quantized at 12 bits.

5. HT – BLOCK DIAGRAM IMPLEMENTATION

In Fig. 6, the demodulation is implemented with a Hilbert discrete transform based on a FIR linear phase filter. It is recommended to choose an odd order FIR filter, because the group delay will be an integer value. After the filtering and delaying processes, the information is split.

In order to calculate the IP amplitude, $A[n]$, the information from the filtering and delaying block are arithmetically squared, added, and root squared. A trigonometric function atan2 is applied to the quotient of imaginary and real parts of IP to calculate instantaneous phase, $\delta[n]$.

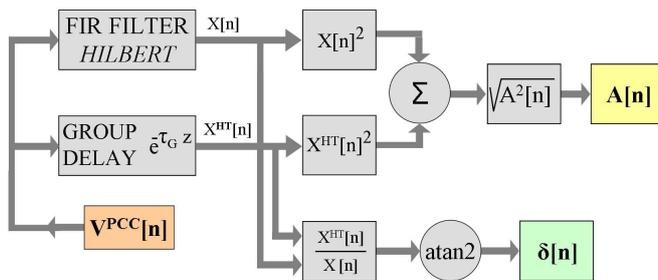


Fig. 6 Complex Envelope Demodulation through discrete HT

6. HILBERT DISCRETE FILTER DESIGN

- There are some consideration in HT discrete filter design:
- Input signal with zero mean value: HT does not allow a DC component.
- The voltage flicker frequency under study spreads in a range $50\text{Hz} \pm 35\text{Hz}$ or $60\text{Hz} \pm 40\text{Hz}$. The lower limits are 15Hz and 20Hz, respectively.

The Parks - McClellan algorithm method design requires the filter order, transitions bands and bandwidth.

The FIR filter design must take into account the transition bands to avoid incorrect operation of demodulation at those frequencies. However the ripple of FIR filter amplitude at pass band should be limited below $\pm 5\%$. In order to design the filter two independent variables must be controlled to assure the requirement, the filter order and transition band.

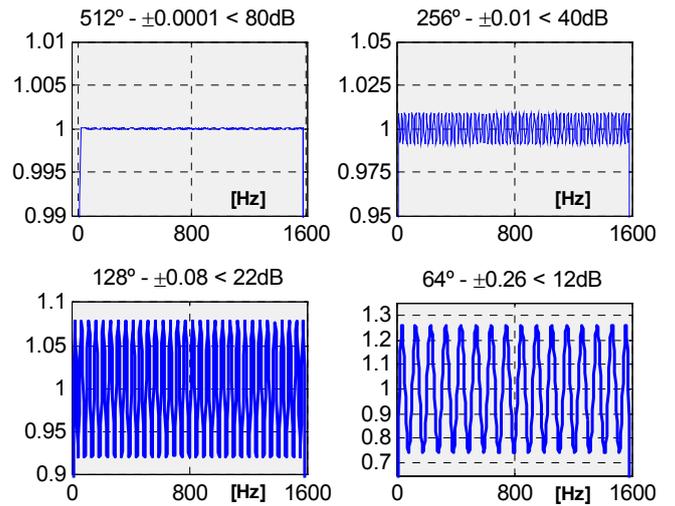


Fig. 7 HT Filter: Order and Ripple comparison over Frequency response

In order to compare different design of discrete HT FIR filters, Fig. 7, shows four cases, at a frequency range of 0 to Nyquist (1600Hz). At first sight, the most important characteristic is the longer the order, the lower the ripple, but implies higher computational burden. Both FIR 256° and 512° order filters perform a low ripple result, below the design threshold of 0.05.

A second comparison is shown in Fig. 8 at a frequency range of $50 \pm 40\text{Hz}$, where ripple, flicker band and transition band are exposed. Again the 512° and 256° filters fulfill the design requirements.

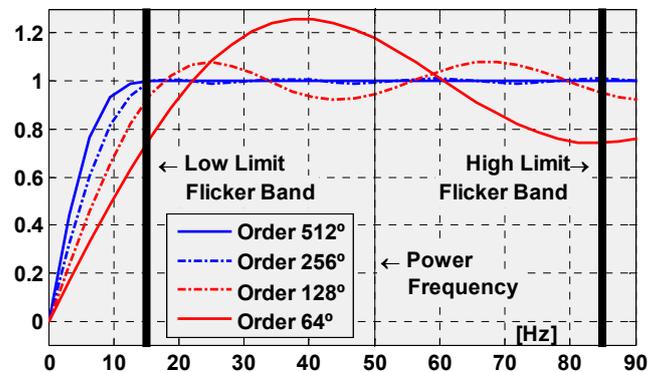


Fig. 8 Ripple and transition band comparisons FIR Hilbert filter frequency responses

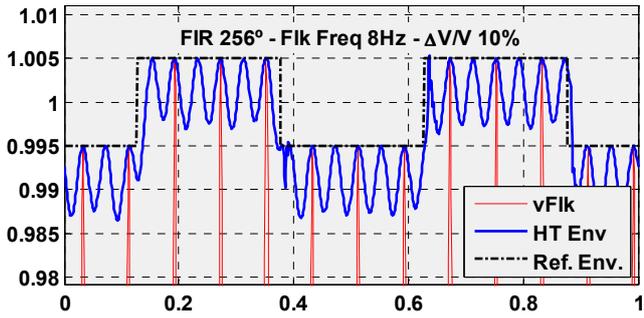
7. LABORATORY EQUIPMENT

The electronic and digital processing laboratory is equipped with a Fluke 6100A Electrical Power Standard. This equipment has enough uncertainty for testing Class A category of [5].

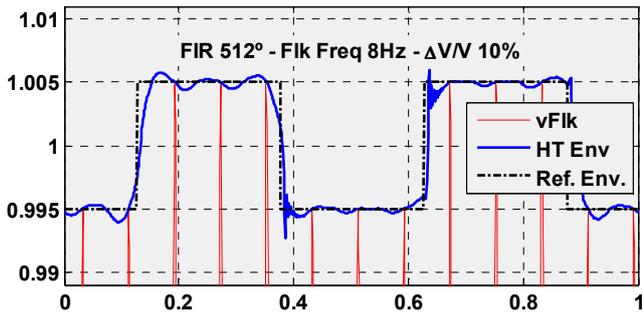
8. FLICKER ENVELOPE TRACKING PERFORMANCE

Fig. 9 (a) and (b) shows the demodulation processes by the discrete HT FIR filter. Two orders are performed as a comparison over a voltage flicker of 50Hz, and $\Delta V/V$ 10% and 8Hz of pulsation. The theoretical modulation is in dashed as a reference (Ref. Env.). The 256° order FIR gives higher level of ripple than the 512° FIR.

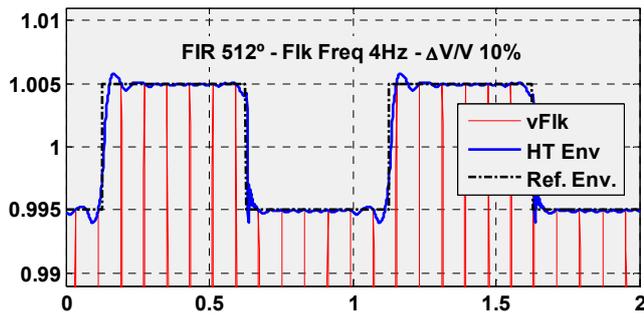
On Fig. 9 (b) and (c) a modulation of $\Delta V/V$ 10% is performed at 512° FIR order. Two modulation were tested at 8Hz and 4 Hz respectively. The ripple amplitude and frequency in both cases are lower than the case of 256°.



(a)



(b)



(c)

Fig. 9 Flicker Envelope Tracking – Three comparison cases

9. FREQUENCY MEASUREMENT PERFORMANCE

The block diagram in Fig. 10 shows the derivative process of instantaneous phasor angle to estimate the power frequency involved between samples, and then is low pass filtered to minimize the noise due to derivation. This process widely satisfy the IEC 61000-4-30 [5] requirement on power frequency measurement, providing a 10s integrated value to

update the sampling frequency of the data acquiring front end with a tolerance lower than $\pm 2,5\text{mHz}$ in a range of $50 \pm 7,5\text{Hz}$, Fig. 11.

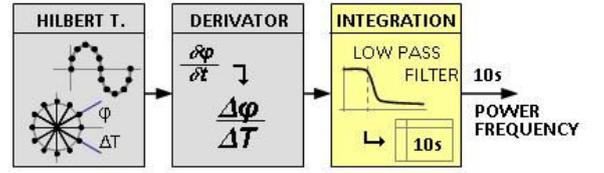


Fig. 10 Frequency Block Diagram

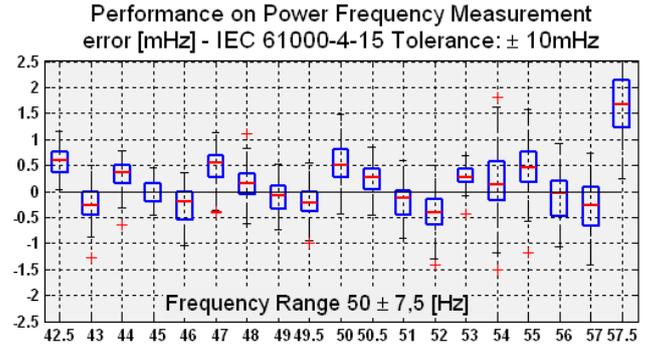


Fig. 11 Frequency error $\leq \pm 2,5\text{mHz}$

10. DEMODULATION DRAWBACK

The demodulation block at a flicker meter process is performed by square multiplier in [6], but this could be replaced by a Hilbert transformer, giving information of envelope amplitude and power frequency, sample per sample.

The Cigré protocol [2] proposed several tests to apply to flicker meters to assure the philosophy of [5] Class A instruments regarding to measurement comparison. The test number 5, specify the following experiment: “Sweep the frequency from 100/120 Hz to 2.0/2.4kHz (50/60Hz) at a maximum 5Hz/s slew rate.” Although isolated harmonics or isolated inter-harmonics over the 2° harmonic do not influence on flicker, spectral components at double the power frequency may change the real flicker value, due to the demodulation process. This phenomena is inherent to the demodulation method utilized.

A voltage signal composed by a power frequency voltage with flicker and a second harmonic, after the demodulation processes will give flicker envelope with a no real flicker component. Its magnitude and frequency is a composition of flicker and harmonic amplitude and frequencies.

The followings equations (5a 5b) to (8) show how the square demodulation process of [6] is affected by a second harmonic. And in equation (9) and (10) how Hilbert process is influenced.

$$\begin{aligned}
 A(t) &= (1 + m_F \cdot \text{Cos}(\omega_F \cdot t)) \\
 \text{Cos}(\omega_1 \cdot t) &> C_1 \quad \& \quad \text{Cos}(\omega_2 \cdot t) > C_2 \\
 u &= A(t) \cdot \text{Cos}(\omega_1 \cdot t) + h_2 \cdot \text{Cos}(\omega_2 \cdot t) \\
 u &= A(t) \cdot C_1 + h_2 \cdot C_2
 \end{aligned}
 \tag{5a}$$

$$\begin{aligned}
u^2 &= A(t)^2 \cdot C_1^2 + h_2^2 \cdot C_2^2 \\
2u^2 &= A(t)^2 \cdot (1 + C_2) + h_2^2 \cdot (1 + C_4) + 4 \cdot A(t) \cdot h_2 \cdot C_1 \cdot C_2 \quad (5b) \\
2u^2 &= A(t)^2 \cdot (1 + C_2) + h_2^2 \cdot (1 + C_4) + 2 \cdot A(t) \cdot h_2 \cdot (C_3 + C_1)
\end{aligned}$$

DC & \gg 50/60Hz

$$\begin{aligned}
2u^2 &= A(t)^2 \cdot (1 + C_2) + 2 \cdot A(t) \cdot h_2 \cdot C_1 \\
2u^2|_{<50/60Hz} &= (1 + m_F \cdot C_F)^2 \cdot (1 + C_2) + 2 \cdot (1 + m_F \cdot C_F) \cdot h_2 \cdot C_1 \\
2u^2|_{<50/60Hz} &= (1 + 2 \cdot m_F \cdot C_F + m_F^2 \cdot C_F^2) \cdot (1 + C_2) + 2 \cdot (1 + m_F \cdot C_F) \cdot h_2 \cdot C_1 \quad (6) \\
2u^2|_{<50/60Hz} &= (1 + 2 \cdot m_F \cdot C_F + m_F^2 \cdot C_F^2) \cdot (1 + C_2) + 2 \cdot h_2 \cdot C_1 + 2 \cdot m_F \cdot h_2 \cdot C_F \cdot C_1
\end{aligned}$$

Standard demodulation process without harmonics nor inter harmonic 50/60Hz

From (6) the third component is extracted to analyze the addition of flicker error

$$\begin{aligned}
2u^2|_{<50/60Hz} &= Std + errorComponent_{50/60Hz} + Error_{2^{\circ}} \\
Error_{2^{\circ}}^2 &= (1 + m_F \cdot C_F) \cdot h_2 \cdot C_1 \\
Error_{2^{\circ}}^2 &= h_2 \cdot C_1 + m_F \cdot h_2 \cdot C_F \cdot C_1 \quad (7) \\
Error_{2^{\circ}}^2|_{<50/60Hz} &= m_F \cdot h_2 \cdot C_F \cdot C_1 \\
Error_{2^{\circ}}^2|_{<50/60Hz} &= (1/2) \cdot m_F \cdot h_2 \cdot \underbrace{(\cos(\omega_1 + \omega_F) + \cos(\omega_1 - \omega_F))}_{>50/60Hz}
\end{aligned}$$

Finally (8) express the error flicker component due to the presence of a second harmonic:

$$uFLK_{2^{\circ}Harm}^{error} = (1/2) \cdot m_F \cdot h_2 \cdot \cos(\omega_1 - \omega_F) \quad (8)$$

The flicker error component due to a Hilbert process, is similar to the square multiplier. Developing the same previous steps, we can see at (9) and (10), the mFLK error:

$$\begin{aligned}
u &= A(t) \cdot C_1 + h_2 \cdot C_2 \\
uHT &= A(t) \cdot S_1 + h_2 \cdot S_2 \quad \text{being } S_x = \sin(\omega_x t) \\
\hat{IP} &= u + j \cdot uHT \quad (9) \\
m^2 &= u^2 + uHT^2
\end{aligned}$$

The HT processes gives an error component of double the square multiplier, but its effect is reduced because the envelope calculation is the root square of the real flicker plus the error component, (10)

$$\begin{aligned}
mFLK_{2^{\circ}Harm}^{error} &= m_F \cdot h_2 \cdot \cos(\omega_1 - \omega_F) \\
mFLK &= \sqrt{mFLK_{STD}^2 + mFLK_{2^{\circ}Harm}^{error}{}^2} \quad (10)
\end{aligned}$$

11. INSTANT FLICKER PERFORMANCE

The IP amplitude is evaluated through the [6] requirements on instant flicker. Working with sinusoidal Fig. 12 and rectangular Fig. 13 modulation, the instant flicker must be unitary with a tolerance lower than $\pm 5\%$.

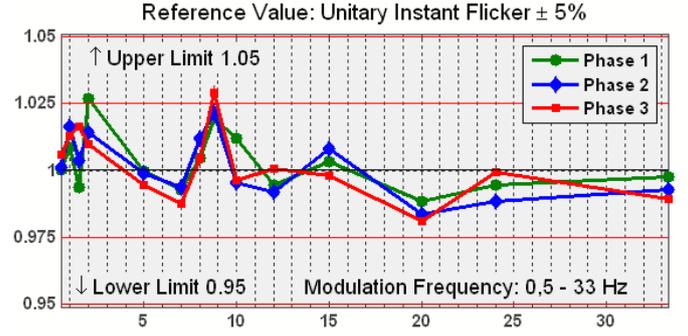


Fig. 12 Envelope Performance on Sinusoidal Modulated Voltage

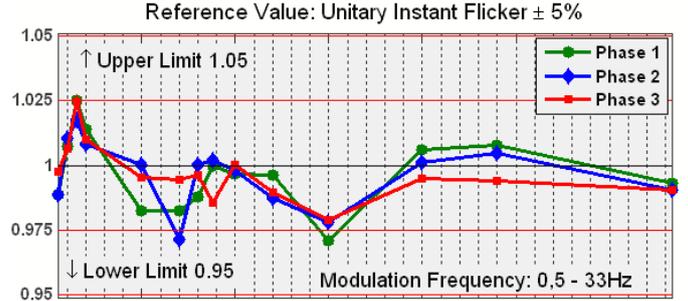


Fig. 13 Envelope Performance on Rectangular Modulated Voltage

CONCLUSIONS

The modulation through the discrete process of Hilbert transform performs a time domain instantaneous phasor. This parameter summarizes sample to sample the magnitude of voltage envelope (phasor) and its spatial or angular position, providing the power frequency measurement.

The information reliability was analyzed by several test on [2], [5] and [6], where the error magnitudes were between two and four times below from error limits.

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